New Margin- and Evidence-Based Approaches for EEG Signal Classification

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• muscles





- muscles
- peripheral nerves





- muscles
- peripheral nerves
- (vision)





- muscles
- peripheral nerves
- (vision)
- (motor cortex)





• Attention shifts to auditory stimuli.





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- Attention shifts to tactile stimuli.

5-class paradigm in MEG (incl. NIC).50-85% correct, avg. 70% across 9 subjects.(Cornelius Raths, MSc awarded 2007)





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 - Manipulation of stimulus type.
 - Optimization of stimulus code according to information-theoretic and psychophysiological factors.

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- Algorithm development.





• Get results quickly:

Shift the burden of learning from the patient to the computer. Hours to recognize the relevant features, rather than weeks/months training a patient to modulate pre-specified features.



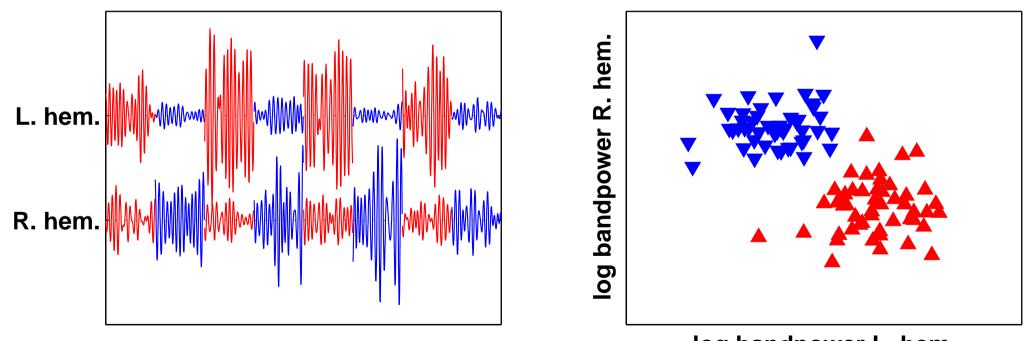


- Get results quickly:
 - Shift the burden of learning from the patient to the computer. Hours to recognize the relevant features, rather than weeks/months training a patient to modulate pre-specified features.
- Let the system run itself:
 - No intervention from experts.





Event-Related Desynchronization in motor imagery: classify imagined left hand movement vs. imagined right hand movement based on α -band power of estimated pre-motor cortex sources in the left and right hemispheres.

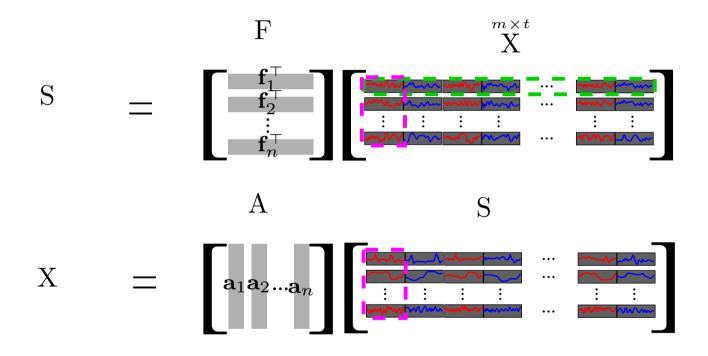


log bandpower L. hem.





Given multichannel time-series X, we want appropriately spatially filtered time-series S = FX that contain only task-relevant information.



e.g.

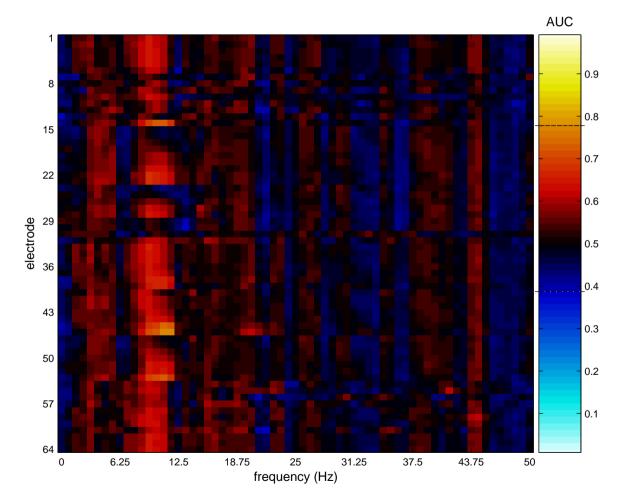
- Independent Component Analysis (ICA)
- Common Spatial Pattern (CSP) Koles 1991.

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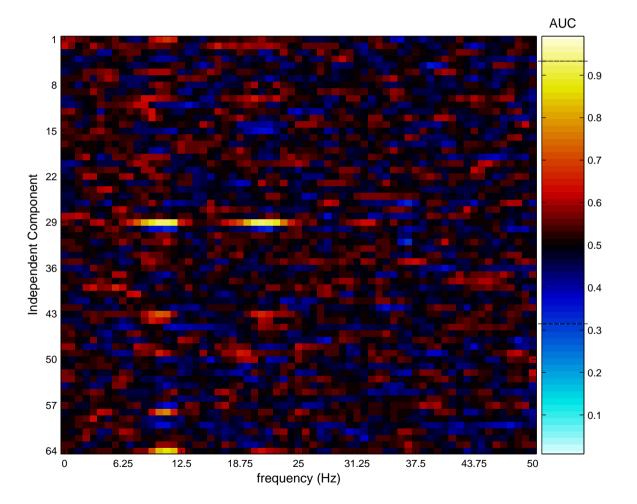
Amplitude spectra of raw EEG signals:





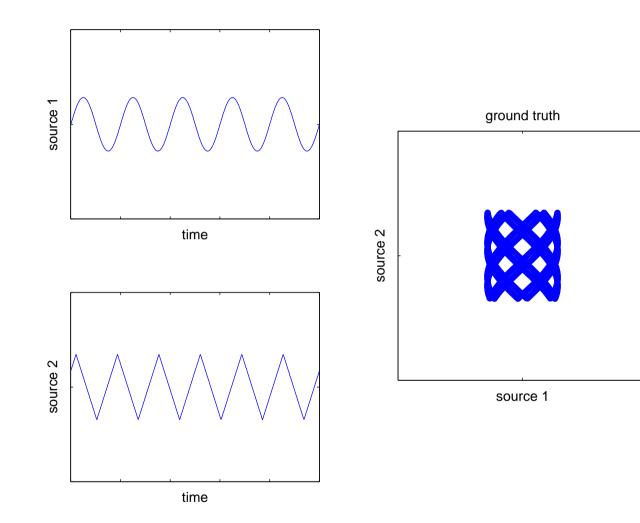


Amplitude spectra of sources estimated by Independent Component Analysis:



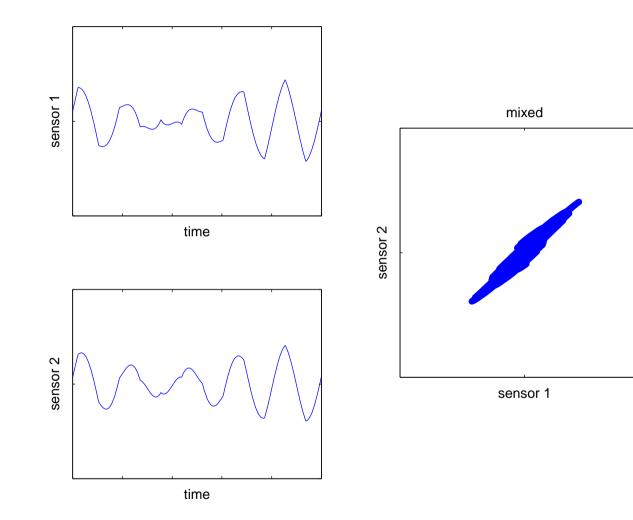






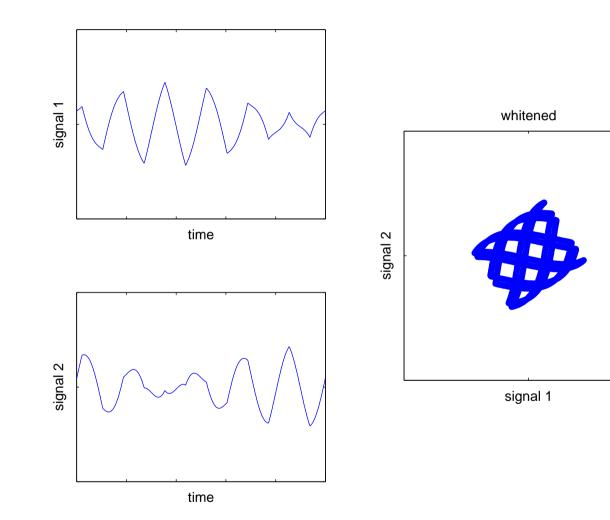






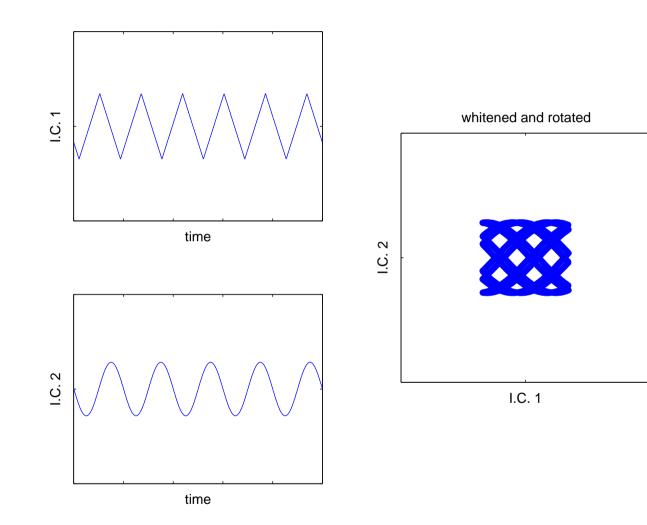






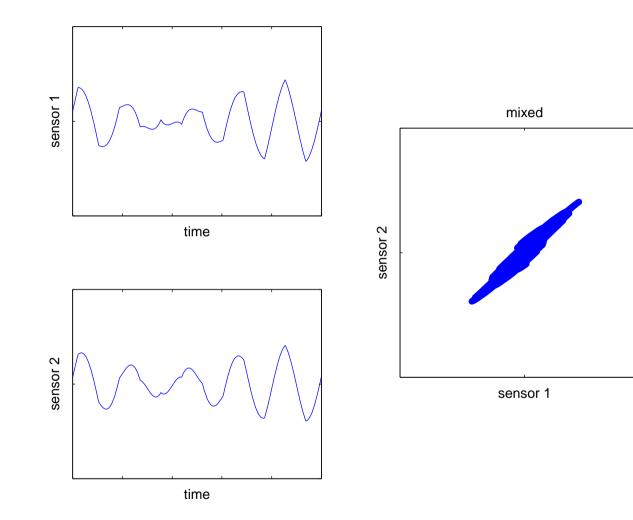






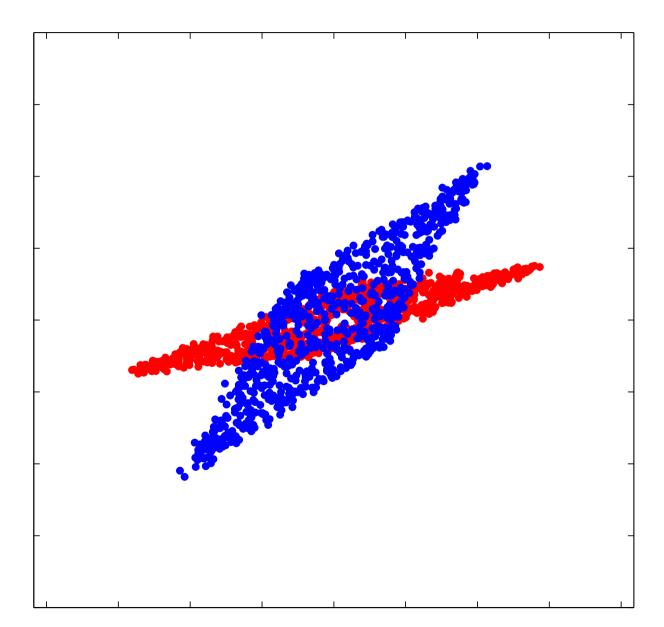






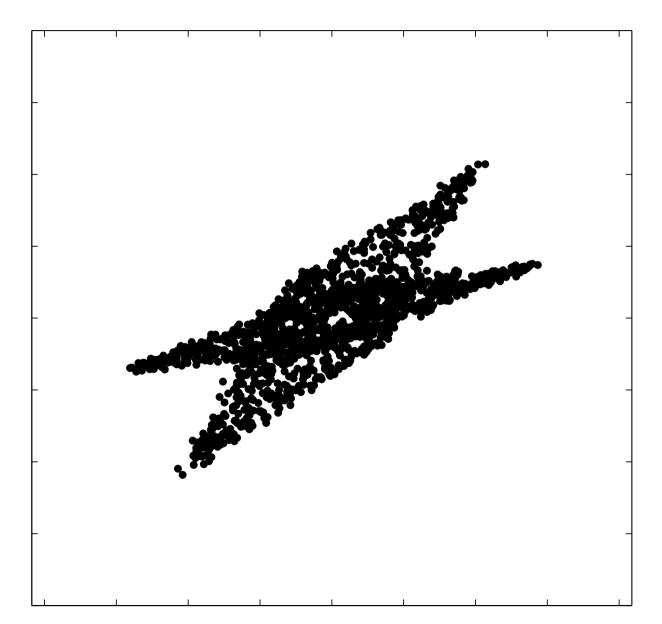






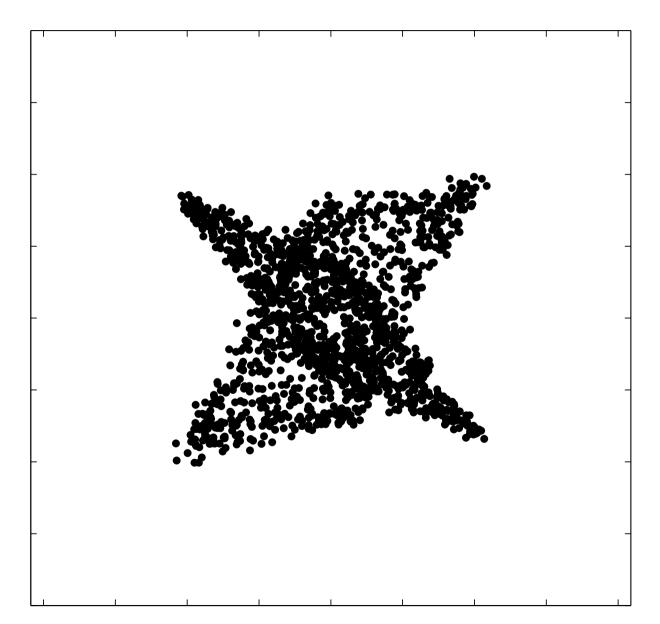






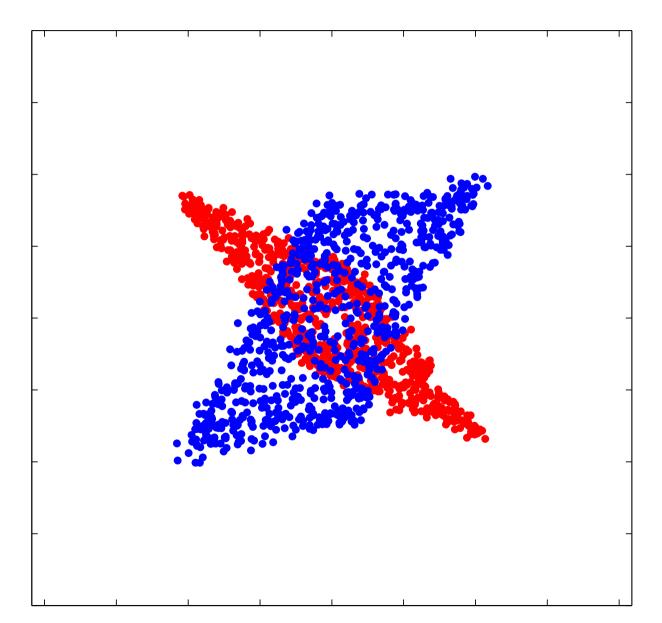






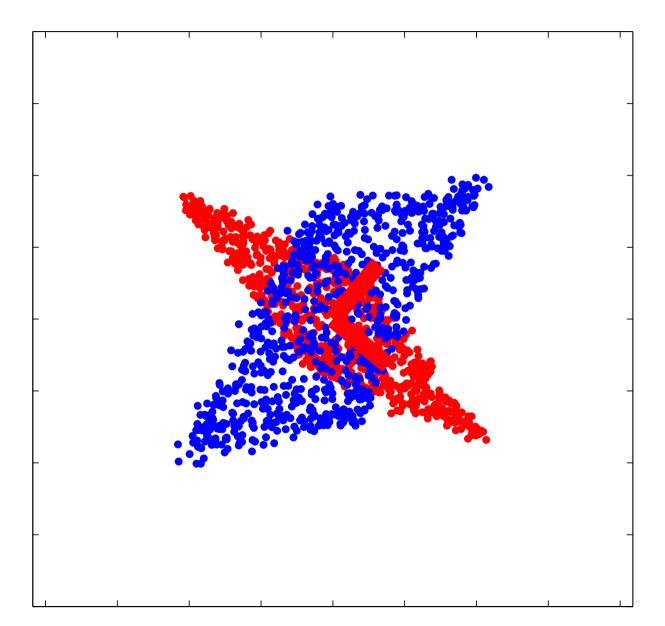






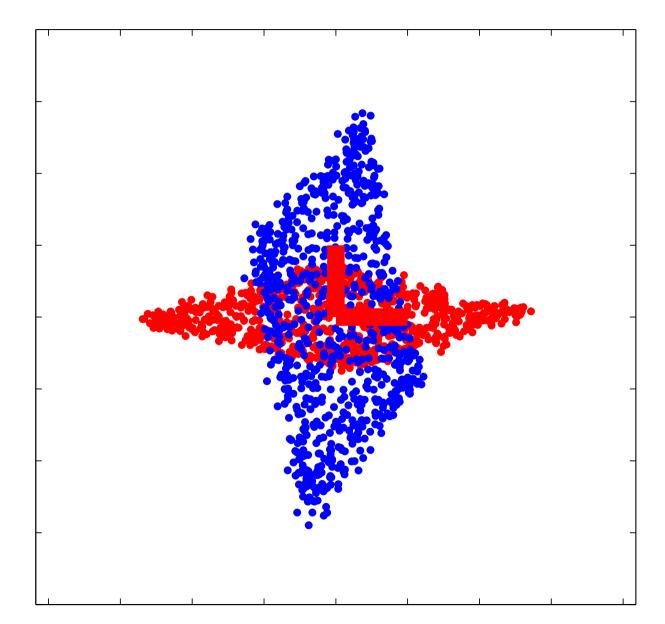






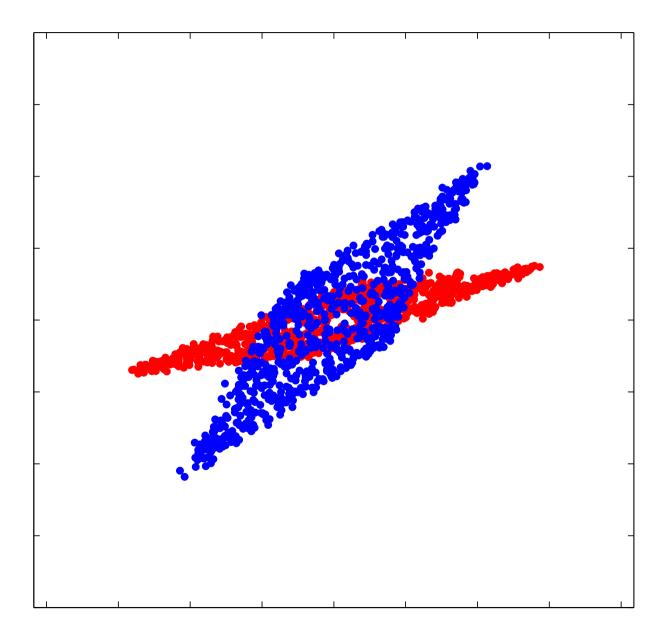






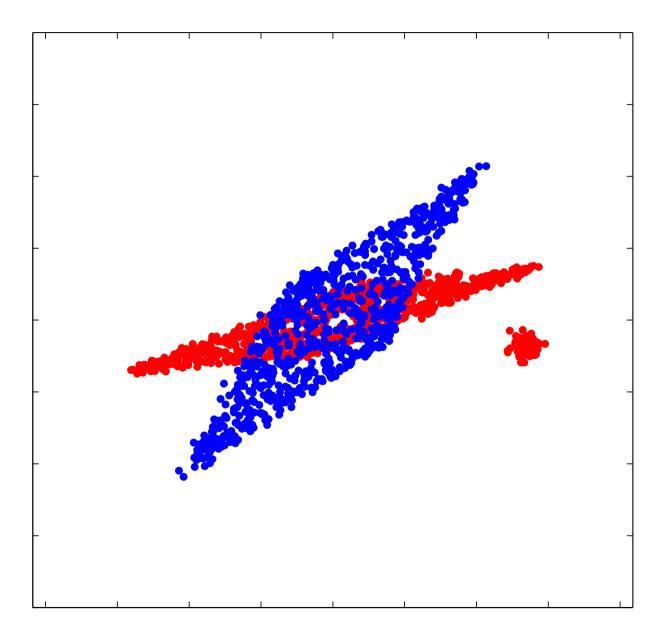










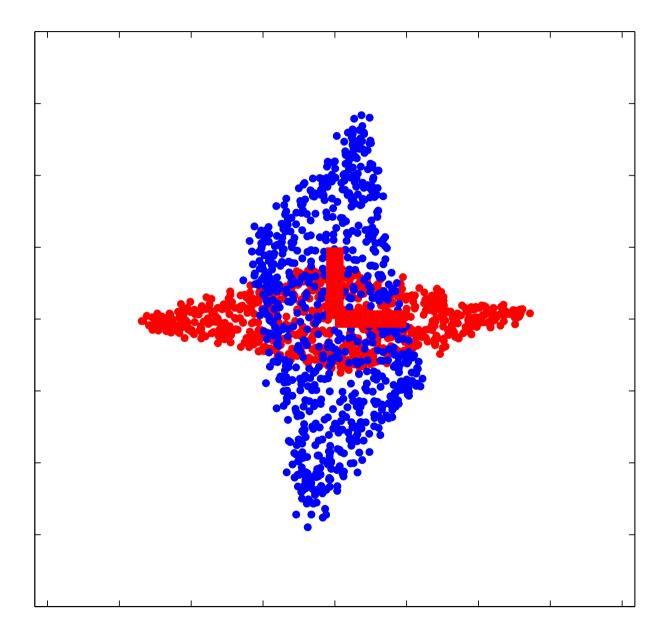


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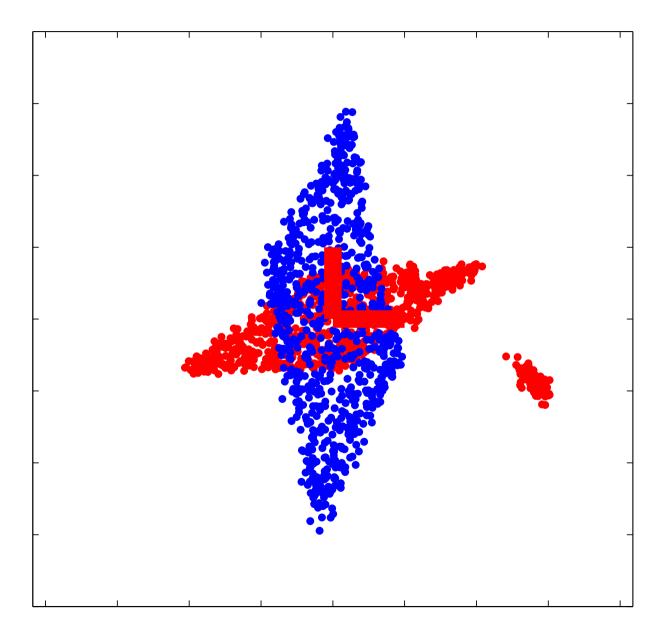








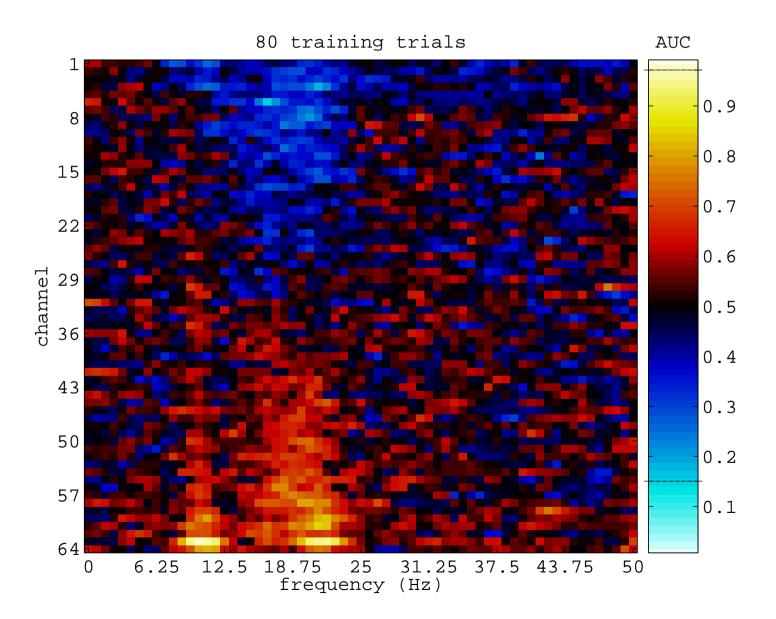




CSP: overfitting



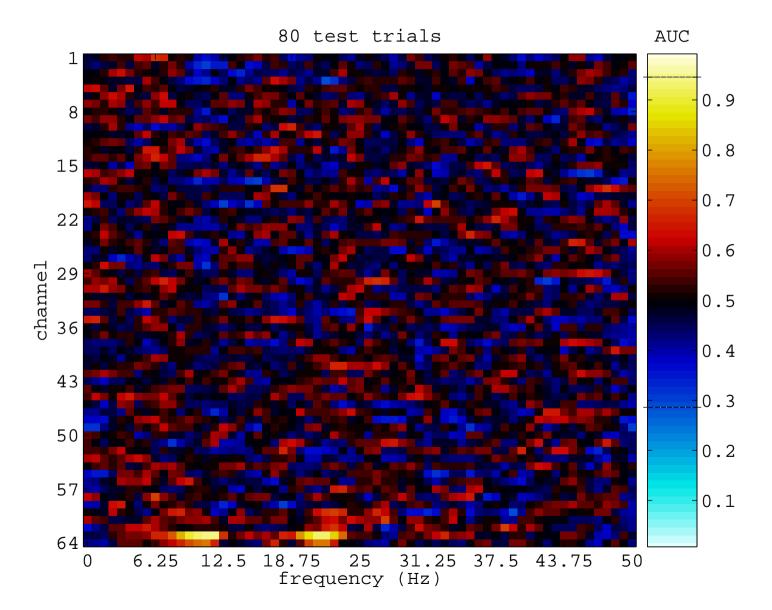




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In practice, component / band / time-window selection is often best performed by

hand. The ideal BCI algorithm would be a "glass box" requiring no such

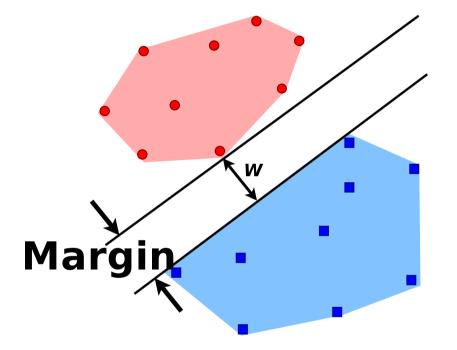
intervention.



Get a better objective (I)



Approach #1: Margin Maximization (à la Support Vector Machine)



Maximize the margin in the space of log bandpower features $\psi(X; F)$.

 $\psi(\mathbf{X}_i; \mathbf{F}) = \log \operatorname{diag}\left(\mathbf{F} \mathbf{X}_i \mathbf{X}_i^{\mathsf{T}} \mathbf{F}^{\mathsf{T}}\right)$

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Approach #1: Margin Maximization (à la Support Vector Machine)

Given time-series X_i and class labels y_i , simultaneously optimize

- spatial filtering coefficients F
- classifier weight-vector \mathbf{w} in log-bandpower space
- classifier bias b in log-bandpower space

to minimize the SVM-like objective function:

$$\lambda \mathbf{w}^{\top} \mathbf{w} + \sum_{i} \max(0, \ 1 - y_i(\psi(\mathbf{X}_i; \mathbf{F})^{\top} \mathbf{w} + b))$$

Regularization parameter λ can be found by cross-validation.



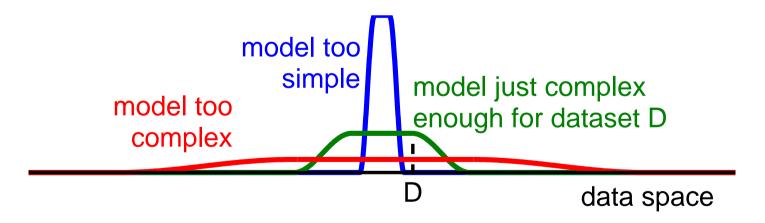


Approach #2: "Evidence" Maximization (using Gaussian Process classifiers)

The marginal likelihood or evidence of a probabilistic model with hyperparameters F is given by integrating the lower-level parameters (e.g. a classifier's weight vector \mathbf{w}) out of the likelihood for data D:

$$P(D|\mathbf{F}) = \int \Pr(D|\mathbf{w}, \mathbf{F})\Pr(\mathbf{w}|\mathbf{F})d\mathbf{w}$$

It is a probability density function, so it normalizes over the space of possible datasets. Maximizing evidence can be an effective means of complexity control and hence model selection:







Approach #2: "Evidence" Maximization (using Gaussian Process classifiers)

• Define a *covariance function* in the log-bandpower space, e.g. a linear covariance function

$$k(\mathbf{X}_i, \mathbf{X}_j) = 1 + \psi(\mathbf{X}_i; \mathbf{F})^\top \psi(\mathbf{X}_j; \mathbf{F})$$

or some other function of ψ for non-linear classification.

• Plug this into a Gaussian Process Classifier

(using Probit likelihood, and the Expectation-Propagation algorithm to approximate it—see Kuss & Rasmussen 2005, Journal of Machine Learning Research 6).

- The Gaussian Process framework yields an expression for the evidence, which is easily differentiable with respect to F.
- So optimize F by conjugate gradient descent.





Both methods were tested on motor-imagery EEG data from 15 subjects:

- 9 from BCI competitions (Comp 2:IIa, Comp 3:IVa,IVc)
- 6 recorded at the MPI (Lal et al 2004, IEEE Trans. Biomed. Eng. 51)





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Preprocessing:

- select time-windows 0.5–4 sec after stimulus presentation
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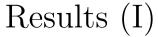
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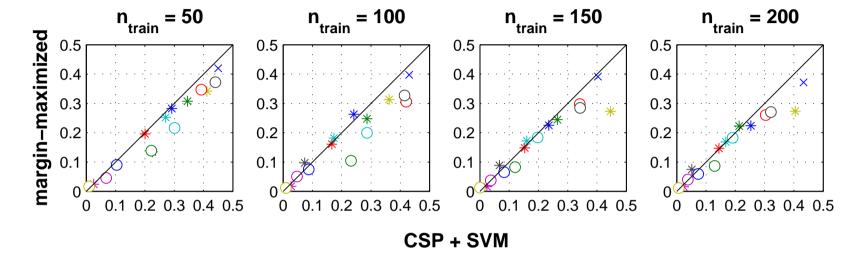
Design:

- Two spatial filters were optimized in each case.
- Performance was assessed as a function of training set size, $n_{\text{train}} \in \{50, 100, 150, 200\}.$
- Each assessment was repeated using 8 random training subsets.





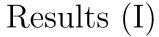




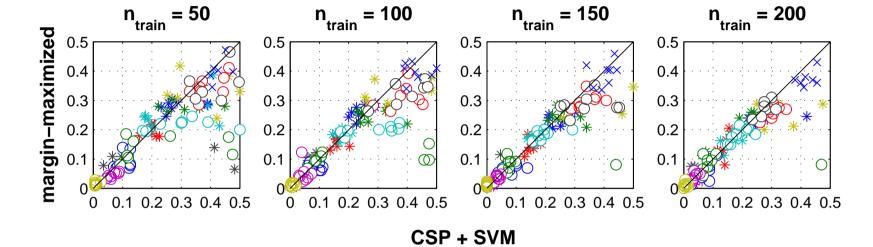
Binary classification error rates:

new approach vs. traditional two-stage CSP + classifier approach.









Note the consistent improvement, most markedly when we have:

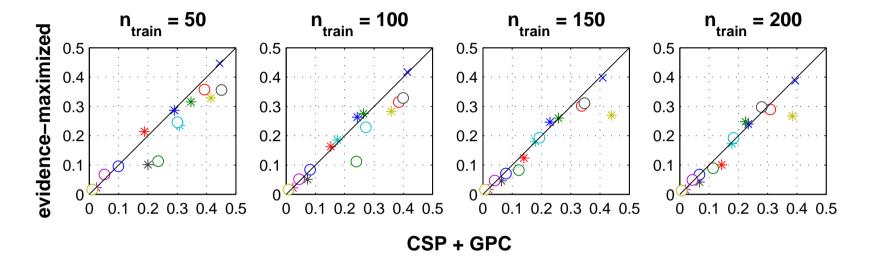
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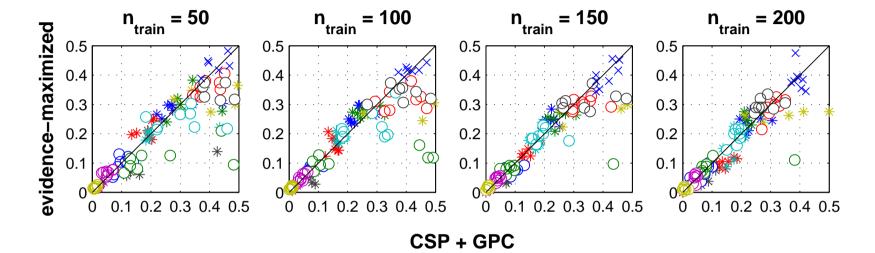
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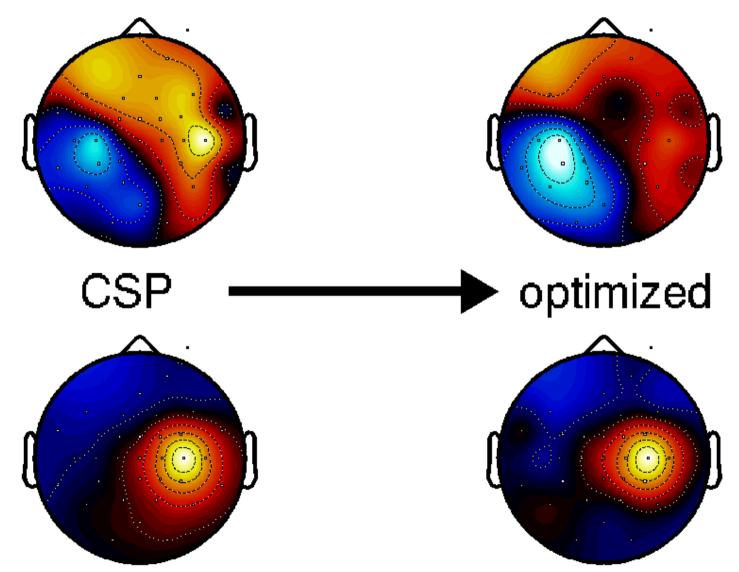
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Spatial Effect of Optimization



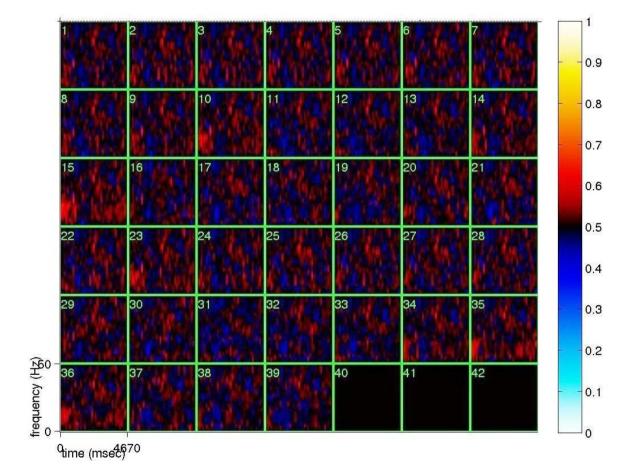
Example of spatial patterns "fixed" by evidence-maximization:



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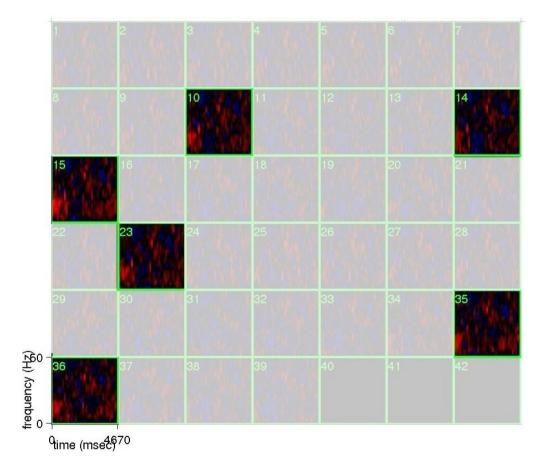








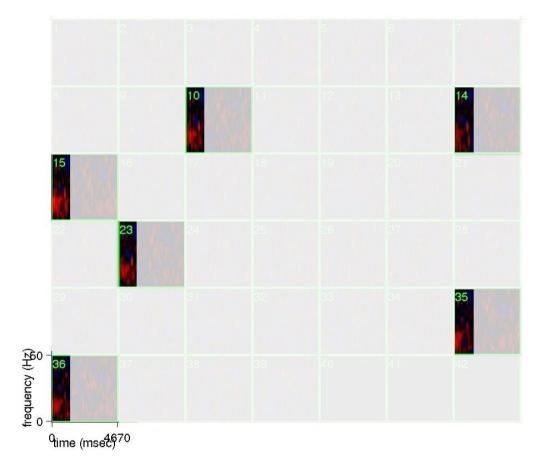




Ideally we want to optimize automatically over space



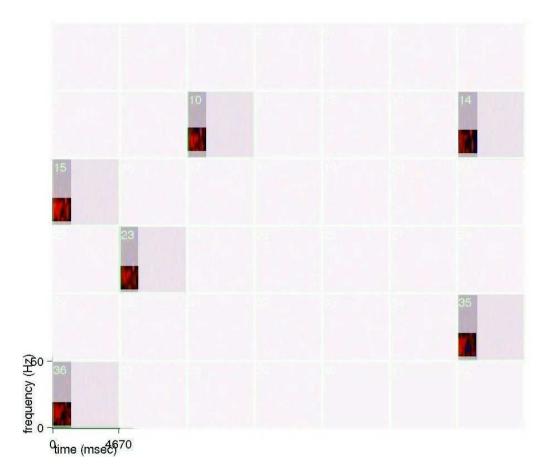




Ideally we want to optimize automatically over space time







Ideally we want to optimize automatically over space

time

frequency





Weightings over time or frequency can be incorporated into our feature mapping:

$$\psi(\mathbf{X}; \mathbf{F}) = \log \operatorname{diag} \left(\mathbf{F} \mathbf{X} \mathbf{X}^{\top} \mathbf{F}^{\top} \right)$$

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Weightings over time or frequency can be incorporated into our feature mapping:

$$\psi(\mathbf{X}; \mathbf{F}, \mathbf{G}) = \log \operatorname{diag} \left(\mathbf{F} \mathbf{X} \ \mathbf{G} \ \mathbf{X}^{\top} \mathbf{F}^{\top} \right)$$



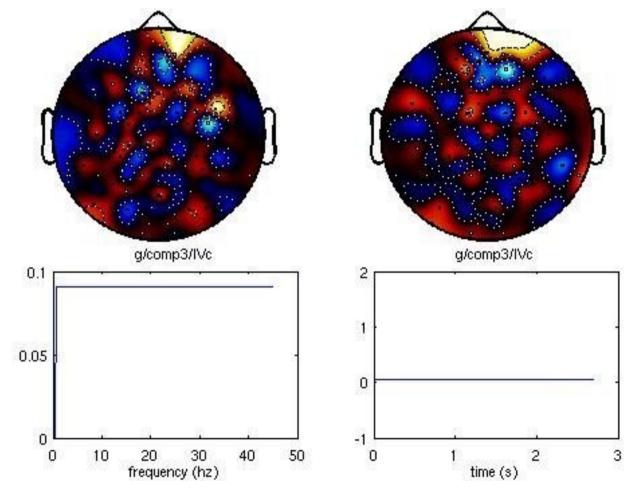


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$$\psi(\mathbf{X}; \mathbf{F}, \mathbf{H}) = \log \operatorname{diag} \left(\mathbf{F} \, \tilde{\mathbf{X}} \, \stackrel{\cdot}{\mathbf{H}} \, \tilde{\mathbf{X}}^{\dagger} \, \mathbf{F}^{\top} \right)$$

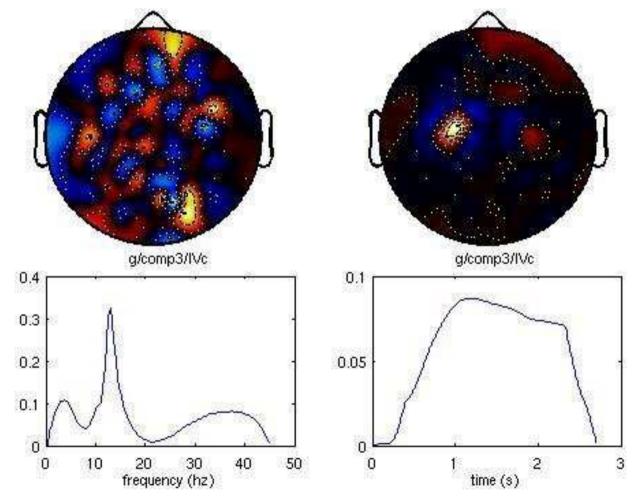






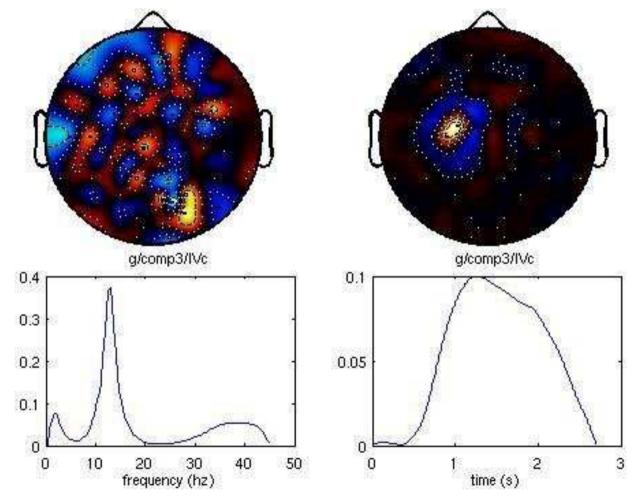








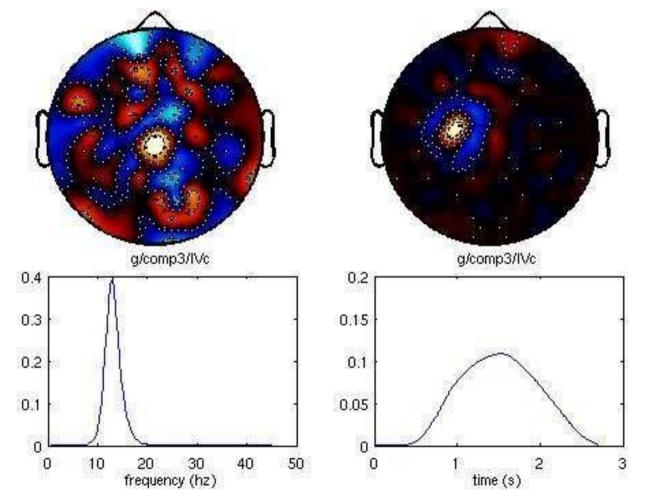








Preliminary experiments by Jason Farquhar show that iterated optimization of F, then G, then H... can yield sensible results with flat initialization over time and frequency, i.e. *without* requiring domain knowledge.

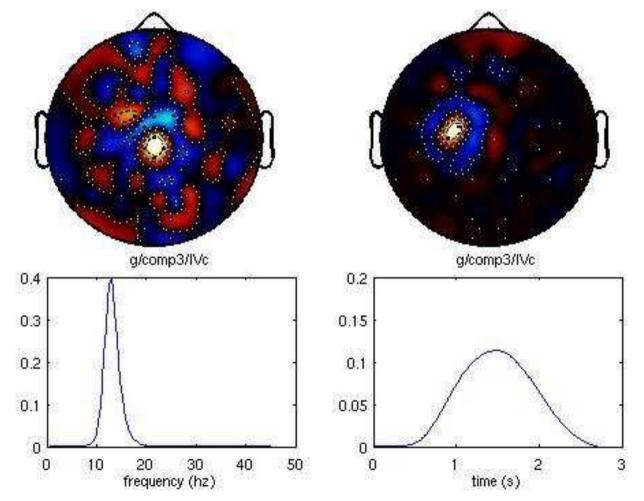


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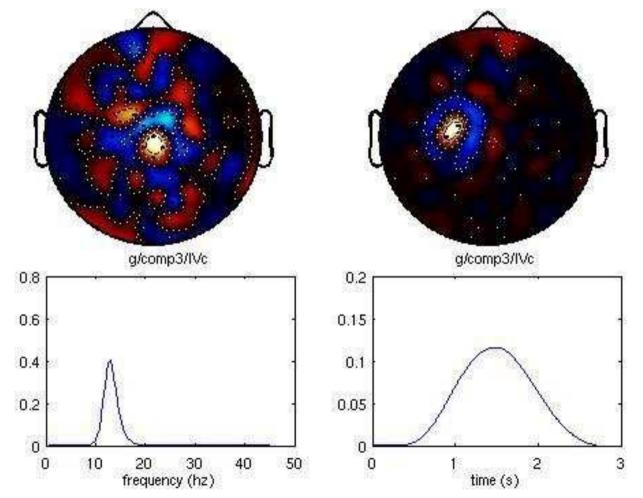
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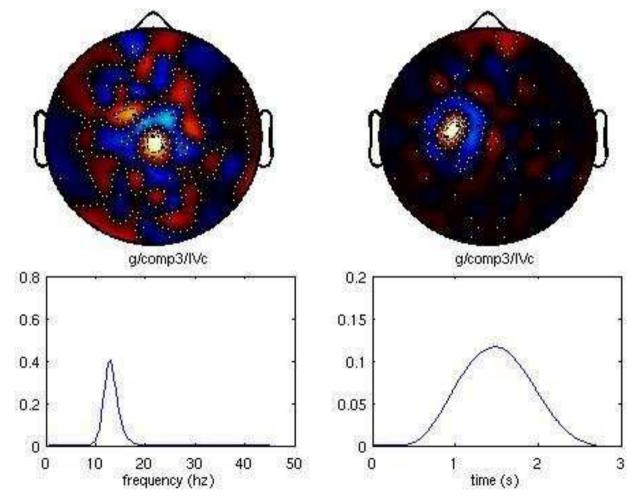






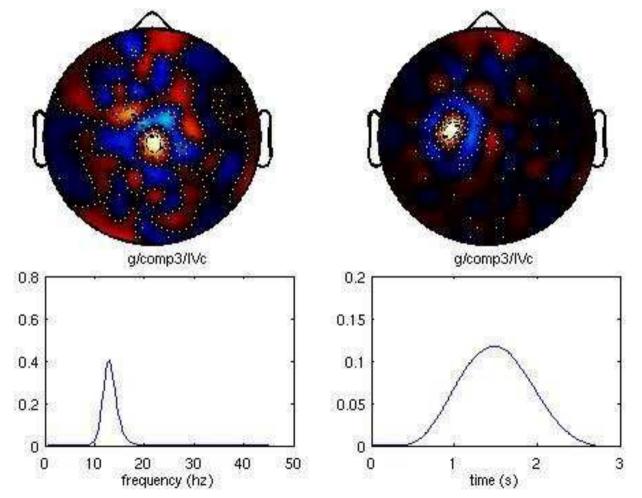








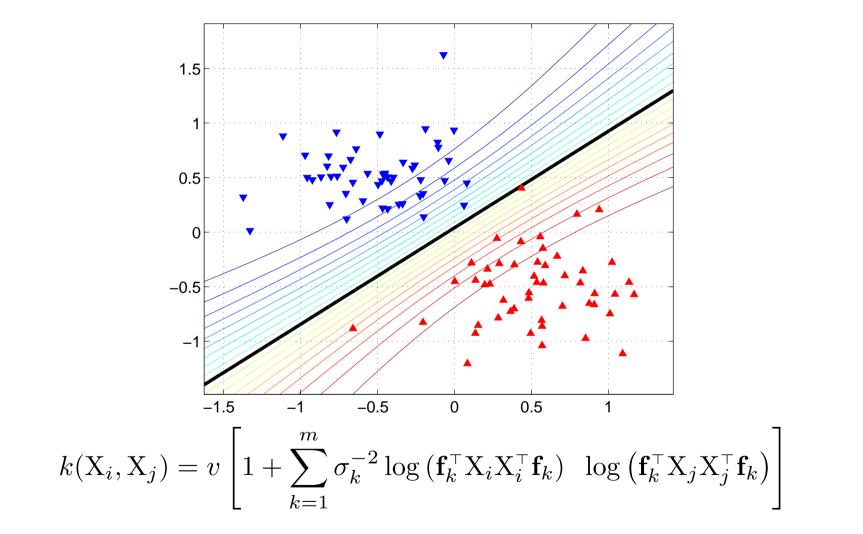






Linear or non-linear?

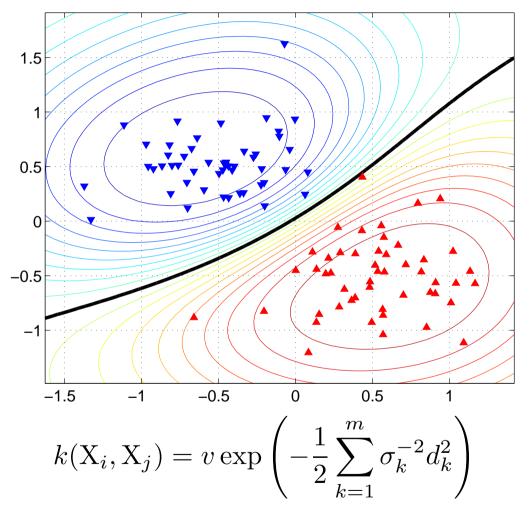






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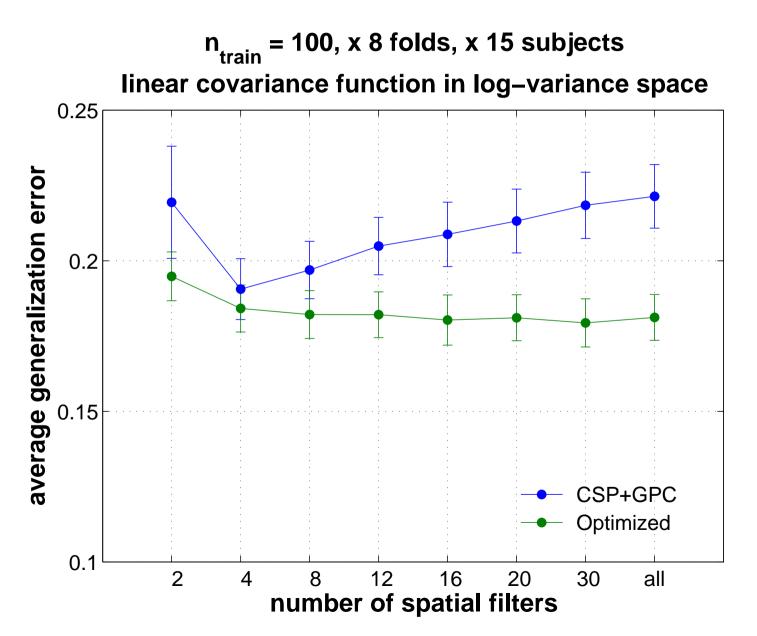
 $d_k = \log\left(\mathbf{f}_k^{\mathsf{T}} \mathbf{X}_i \mathbf{X}_i^{\mathsf{T}} \mathbf{f}_k\right) - \log\left(\mathbf{f}_k^{\mathsf{T}} \mathbf{X}_j \mathbf{X}_j^{\mathsf{T}} \mathbf{f}_k\right)$

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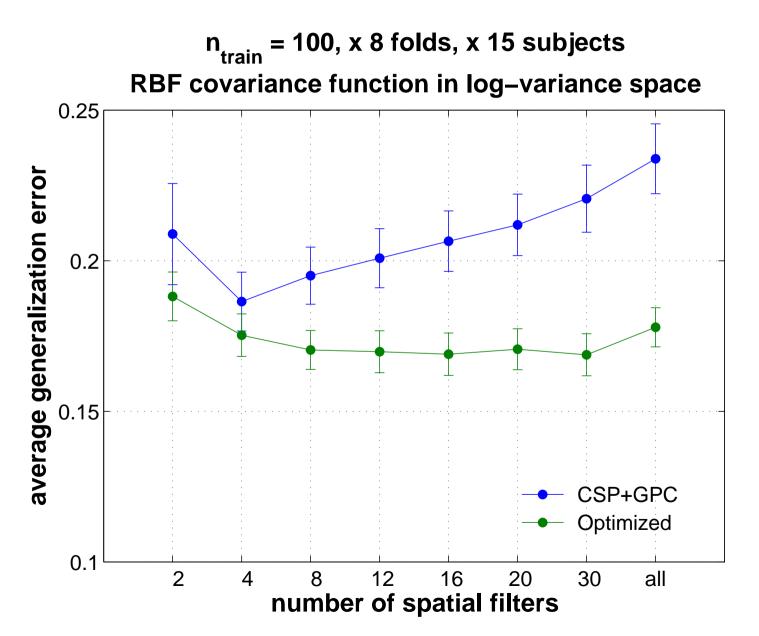












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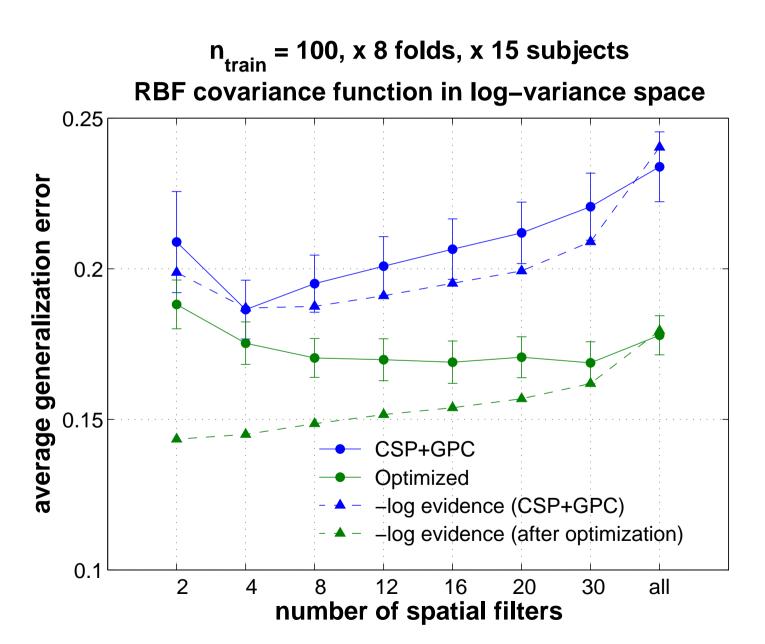
Use of the classifier's criterion to optimize preprocessing parameters means

- projection into higher-dimensional feature spaces via a non-linear kernel can help;
- not just "any classifier will do."

See also: Tomioka et al. (NIPS 2006) - logistic regression on (non-logged) variance features.



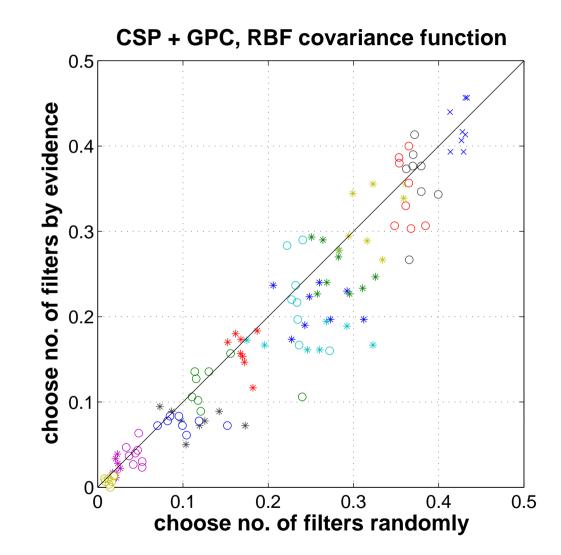




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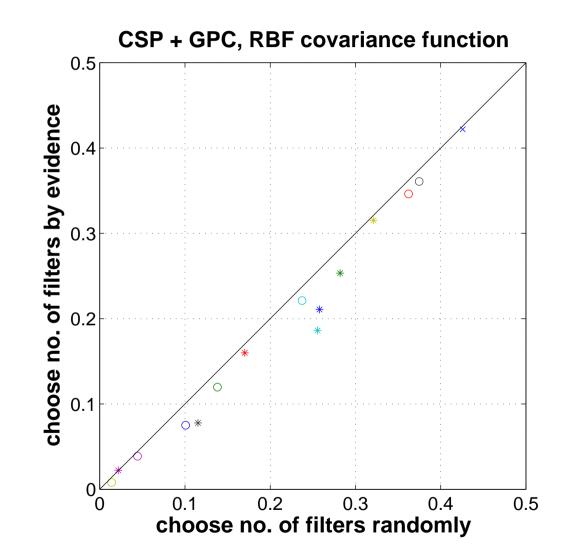






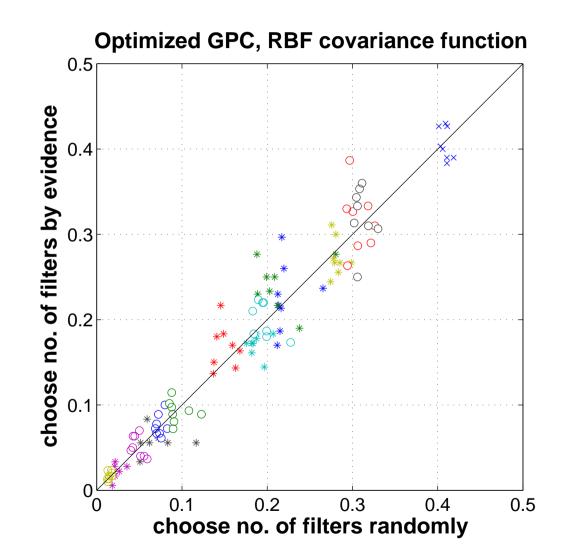






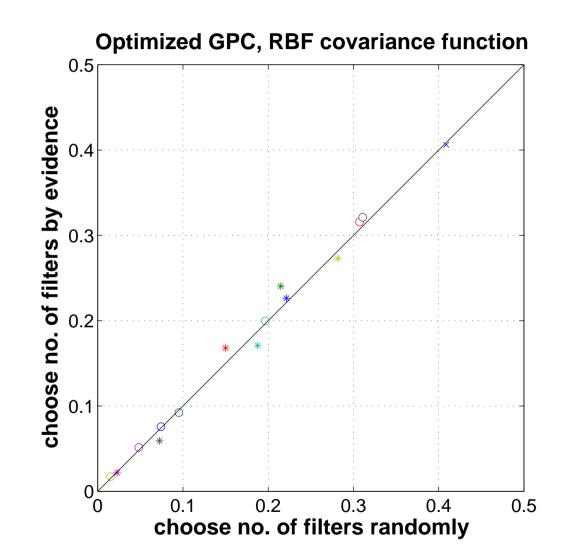






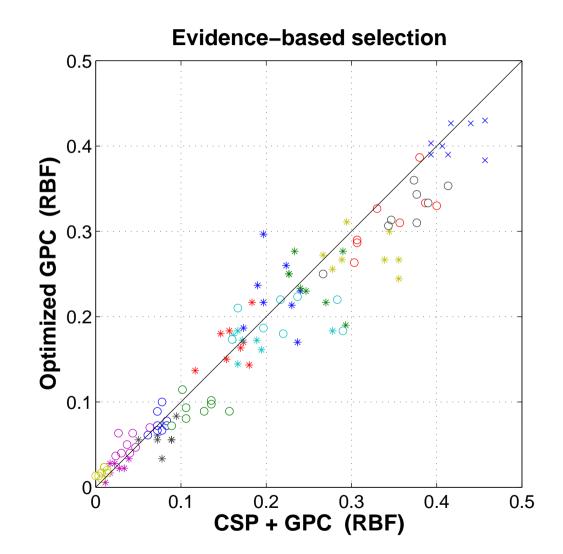






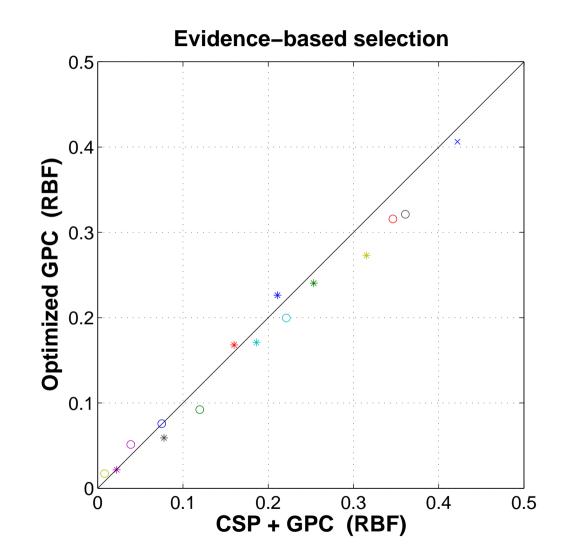














Further goals



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- Adapting the system to cope with shifts in background activity between training and test sessions.
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- Application of the same approach to features in the time domain (and automatic combination of time-domain & band-power features).





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- Benefits are greatest in the difficult cases: high noise and/or small amounts of data.
- Simultaneous optimization of filters and classifier weights eliminates the need to select filters by hand.
- Early indications are that interpretable, optimal weightings across space, time and frequency can be obtained
 - simultaneously;
 - without being very sensitive to prior assumptions.

Thank you for your attention.